

National Exams May 2012
04-CHEM-B1, Transport Phenomena
3 hours duration

NOTES

1. If doubt exists as to the interpretation of any question, the candidate is urged to submit with the answer paper, a clear statement of any assumptions made.
2. The examination is an OPEN BOOK EXAM.
3. Candidates may use any **non-communicating** calculator.
4. **Not all** problems are of equal weight.
5. **Answer all four questions.**
6. State all assumptions clearly.
7. The various conservation equations (momentum, energy, and continuity) are given in Tables 1-4 appended to this paper taken from Brodkey, R.S. and Hershey H.C. (1988) *Transport Phenomena – A Unified Approach*.

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- Q1. [20 marks] Consider the system shown in Fig. 1, in which a cylindrical rod is being moved axially in the z -direction with velocity U . The rod and the cylinder are co-axial. The inner radius of the cylinder is R and the diameter of the rod κR such that $\kappa < 1$. Problems of this kind arise in the analysis of wire-coating dies such as those used in processing of thermoplastic materials.

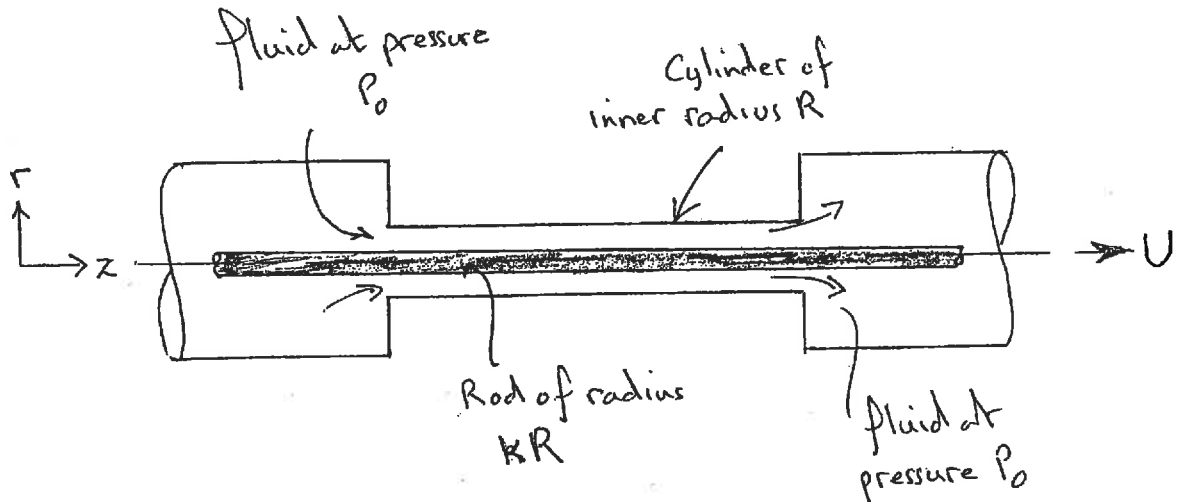


Fig. 1: Annular flow with inner cylinder moving axially

Starting with the appropriate form of the Navier-Stokes equations [see Table 1 on p 5], show that the steady-state velocity profile is given by:

$$u_z = U \frac{\ln(r/R)}{\ln(\kappa)}$$

Furthermore, show that the volumetric flow rate, \dot{V} , is given by:

$$\dot{V} = \frac{\pi R^2 U}{2} \left[\frac{1}{\ln(\kappa)} (\kappa^2 - 1) - 2\kappa^2 \right]$$

- Q2. [30 marks] A plane slab, of thickness $2L$ and thermal conductivity k , uniformly generates heat throughout at a rate \dot{T}_G . The temperatures at the left and right faces are T_1 (at $x = -L$) and T_2 (at $x = +L$). Starting with the appropriate form of the energy equation [see Table 3 on p 7], show that the steady-state temperature profile throughout the slab is:

$$T(x) = T_1 + \frac{\dot{T}_G}{2k} (L^2 - x^2) + \frac{(T_2 - T_1)}{2} \left(1 + \frac{x}{L} \right)$$

If both faces are in contact with air at T_∞ and the convective heat transfer coefficient at the left face is h_1 , and that at the right face is h_2 , develop expressions for the surface temperatures T_1 and T_2 .

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Q3. [20 marks] An important unit operation is the absorption of one of the constituents of a gas mixture preferentially in a contacting liquid. In some cases, depending upon the nature of the molecules, the absorption may or may not involve simultaneous chemical reaction. Consider a liquid surface being exposed to a gas mixture that contains a component A , which preferentially dissolves in the liquid B as shown in Fig. 2. At the liquid surface the concentration of A is C_{A_0} . Throughout the liquid A disappears according to a first-order chemical reaction with a specific reaction rate constant k_1 . At some depth δ within the liquid the concentration of A will have reached zero.

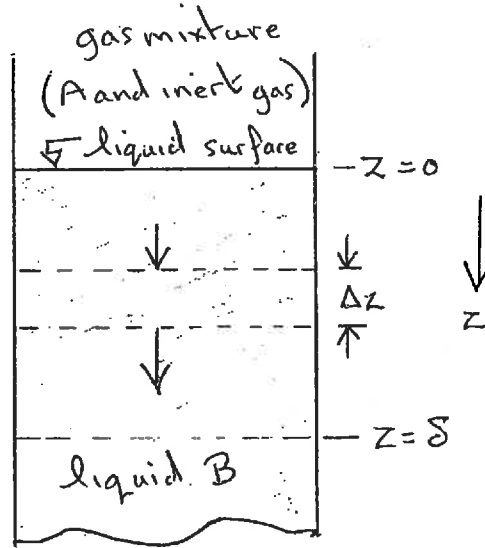


Fig. 2: Absorption of gas A in liquid b with chemical reaction

Starting with the appropriate form of the species continuity equation [see Table 4 on p 7], show that the concentration profile of A within the liquid B , is given by:

$$C_A = C_{A_0} \left\{ \cosh(mz) - \frac{\sinh(mz)}{\tanh(m\delta)} \right\}$$

in which $m = \sqrt{k_1/D_{AB}}$.

Note: The general solution to differential equations of the form $ay - b \frac{d^2y}{dx^2} = 0$ is given by

$$y = C_1 \cosh[\sqrt{a/b} \cdot x] + C_2 \sinh[\sqrt{a/b} \cdot x]$$

Q4. [30 marks] Figure 3 shows a liquid falling as a thin film under laminar flow down a vertical flat surface whilst being exposed to a gas A , which dissolves in the liquid. The liquid contains a uniform concentration of A (C_{A_0}) at the top ($z = 0$), and at the liquid surface ($x = 0$) the concentration of gas is (C_{A_1}).

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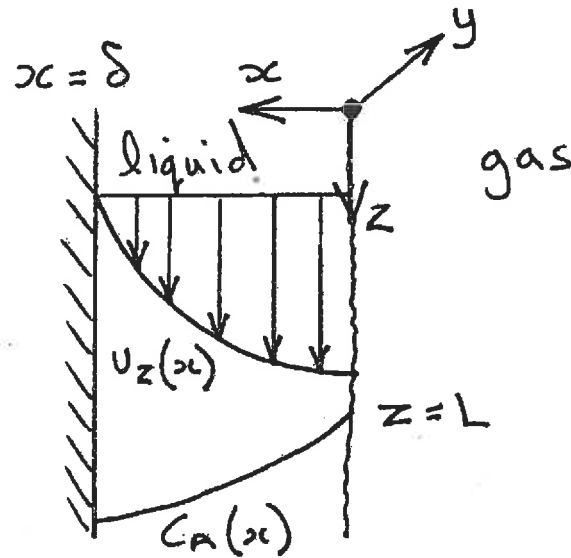


Fig. 3: Falling liquid film

Since this is a problem of fluid flow and mass transfer, first select the appropriate form of the Navier-Stokes equation [see Table 1 on p 5] and develop an expression for the applicable velocity distribution. Then select the appropriate form of the continuity equation for species *A* [see Table 4 on p 7], make the necessary simplifying assumptions and utilizing the resultant velocity distribution show that the governing differential equation for the problem is:

$$\left\{ \rho g_z \delta^2 \frac{[1 - (x/\delta)^2]}{2\mu} \right\} \frac{\partial C_A}{\partial z} = D \frac{\partial^2 C_A}{\partial x^2}$$

Define the boundary conditions but do not attempt to solve the equation.

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Table 1: The Navier-Stokes equations for fluids of constant ρ and μ^1

Navier-Stokes equation in vector form (rectangular coordinates only)	
$\frac{\partial \mathbf{U}}{\partial t} + (\mathbf{U} \cdot \nabla) \mathbf{U} = -\frac{1}{\rho} \nabla p + \mathbf{g} + \nu (\nabla^2 \mathbf{U})$ (5.15)	
Rectangular coordinates	
x component:	$\frac{\partial U_x}{\partial t} + U_x \frac{\partial U_x}{\partial x} + U_y \frac{\partial U_x}{\partial y} + U_z \frac{\partial U_x}{\partial z} = -\frac{1}{\rho} \left(\frac{\partial p}{\partial x} \right) + g_x + \nu \left(\frac{\partial^2 U_x}{\partial x^2} + \frac{\partial^2 U_x}{\partial y^2} + \frac{\partial^2 U_x}{\partial z^2} \right)$ (A)
y component:	$\frac{\partial U_y}{\partial t} + U_x \frac{\partial U_y}{\partial x} + U_y \frac{\partial U_y}{\partial y} + U_z \frac{\partial U_y}{\partial z} = -\frac{1}{\rho} \left(\frac{\partial p}{\partial y} \right) + g_y + \nu \left(\frac{\partial^2 U_y}{\partial x^2} + \frac{\partial^2 U_y}{\partial y^2} + \frac{\partial^2 U_y}{\partial z^2} \right)$ (B)
z component:	$\frac{\partial U_z}{\partial t} + U_x \frac{\partial U_z}{\partial x} + U_y \frac{\partial U_z}{\partial y} + U_z \frac{\partial U_z}{\partial z} = -\frac{1}{\rho} \left(\frac{\partial p}{\partial z} \right) + g_z + \nu \left(\frac{\partial^2 U_z}{\partial x^2} + \frac{\partial^2 U_z}{\partial y^2} + \frac{\partial^2 U_z}{\partial z^2} \right)$ (C)
Cylindrical coordinates	
r component:	$\begin{aligned} \frac{\partial U_r}{\partial t} + U_r \frac{\partial U_r}{\partial r} + \frac{U_\theta}{r} \frac{\partial U_r}{\partial \theta} + U_z \frac{\partial U_r}{\partial z} - \frac{U_\theta^2}{r} \\ = -\frac{1}{\rho} \left(\frac{\partial p}{\partial r} \right) + g_r + \nu \left(\frac{\partial^2 U_r}{\partial r^2} + \frac{\nu}{r} \frac{\partial U_r}{\partial r} - \nu \left(\frac{U_r}{r^2} \right) + \frac{\nu}{r^2} \frac{\partial^2 U_r}{\partial \theta^2} - \frac{2\nu}{r^2} \frac{\partial U_\theta}{\partial \theta} + \nu \frac{\partial^2 U_r}{\partial z^2} \right) \end{aligned}$ (D)
θ component:	$\begin{aligned} \frac{\partial U_\theta}{\partial t} + U_r \frac{\partial U_\theta}{\partial r} + \frac{U_\theta}{r} \frac{\partial U_\theta}{\partial \theta} + U_z \frac{\partial U_\theta}{\partial z} + \frac{U_r U_\theta}{r} \\ = -\frac{1}{\rho r} \frac{\partial p}{\partial \theta} + g_\theta + \nu \left(\frac{\partial^2 U_\theta}{\partial r^2} + \frac{\nu}{r} \frac{\partial U_\theta}{\partial r} - \nu \left(\frac{U_\theta}{r^2} \right) + \frac{\nu}{r^2} \frac{\partial^2 U_\theta}{\partial \theta^2} + \frac{2\nu}{r^2} \frac{\partial U_r}{\partial \theta} + \nu \frac{\partial^2 U_\theta}{\partial z^2} \right) \end{aligned}$ (E)
z component:	$\begin{aligned} \frac{\partial U_z}{\partial t} + U_r \frac{\partial U_z}{\partial r} + \frac{U_\theta}{r} \frac{\partial U_z}{\partial \theta} + U_z \frac{\partial U_z}{\partial z} \\ = -\frac{1}{\rho} \frac{\partial p}{\partial z} + g_z + \nu \left(\frac{\partial^2 U_z}{\partial r^2} + \frac{\nu}{r} \frac{\partial U_z}{\partial r} + \frac{\nu}{r^2} \frac{\partial^2 U_z}{\partial \theta^2} + \nu \frac{\partial^2 U_z}{\partial z^2} \right) \end{aligned}$ (F)
Spherical coordinates	
r component:	$\begin{aligned} \frac{\partial U_r}{\partial t} + U_r \frac{\partial U_r}{\partial r} + \frac{U_\theta}{r} \frac{\partial U_r}{\partial \theta} + \left(\frac{U_\phi}{r \sin \theta} \right) \frac{\partial U_r}{\partial \phi} - \frac{U_\theta^2}{r} - \frac{U_\phi^2}{r} = -\frac{1}{\rho} \frac{\partial p}{\partial r} + g_r + \frac{\nu}{r^2} \left(\frac{\partial}{\partial r} \left(r^2 \frac{\partial U_r}{\partial r} \right) \right) \\ + \left(\frac{\nu}{r^2 \sin \theta} \right) \left(\frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial U_r}{\partial \theta} \right) \right) + \left(\frac{\nu}{r^2 \sin^2 \theta} \right) \left(\frac{\partial^2 U_r}{\partial \phi^2} \right) - \frac{2\nu U_r}{r^2} \\ - \frac{2\nu}{r^2} \frac{\partial U_\theta}{\partial \theta} - \frac{2\nu U_\theta}{r^2} \cot \theta - \left(\frac{2\nu}{r^2 \sin \theta} \right) \frac{\partial U_\phi}{\partial \phi} \end{aligned}$ (G)
θ component:	$\begin{aligned} \frac{\partial U_\theta}{\partial t} + U_r \frac{\partial U_\theta}{\partial r} + \frac{U_\theta}{r} \frac{\partial U_\theta}{\partial \theta} + \left(\frac{U_\phi}{r \sin \theta} \right) \left(\frac{\partial U_\theta}{\partial \phi} \right) + \frac{U_r U_\theta}{r} - \frac{U_\phi^2}{r} \cot \theta \\ = -\frac{1}{\rho r} \frac{\partial p}{\partial \theta} + g_\theta + \frac{\nu}{r^2} \left(\frac{\partial}{\partial r} \left(r^2 \frac{\partial U_\theta}{\partial r} \right) \right) + \left(\frac{\nu}{r^2 \sin \theta} \right) \left(\frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial U_\theta}{\partial \theta} \right) \right) + \left(\frac{\nu}{r^2 \sin^2 \theta} \right) \frac{\partial^2 U_\theta}{\partial \phi^2} \\ + \frac{2\nu}{r^2} \frac{\partial U_r}{\partial \theta} - \left(\frac{\nu U_\theta}{r^2 \sin^2 \theta} \right) - \left(\frac{2\nu \cos \theta}{r^2 \sin^2 \theta} \right) \frac{\partial U_\phi}{\partial \phi} \end{aligned}$ (H)
ϕ component:	$\begin{aligned} \frac{\partial U_\phi}{\partial t} + U_r \frac{\partial U_\phi}{\partial r} + \frac{U_\theta}{r} \frac{\partial U_\phi}{\partial \theta} + \left(\frac{U_\phi}{r \sin \theta} \right) \frac{\partial U_\phi}{\partial \phi} + \frac{U_r U_\phi}{r} + \frac{U_\theta U_\phi}{r} \cot \theta \\ = -\left(\frac{1}{\rho r \sin \theta} \right) \frac{\partial p}{\partial \phi} + g_\phi + \frac{\nu}{r^2} \left(\frac{\partial}{\partial r} \left(r^2 \frac{\partial U_\phi}{\partial r} \right) \right) + \left(\frac{\nu}{r^2 \sin \theta} \right) \left(\frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial U_\phi}{\partial \theta} \right) \right) \\ + \left(\frac{\nu}{r^2 \sin^2 \theta} \right) \frac{\partial^2 U_\phi}{\partial \phi^2} - \left(\frac{\nu U_\phi}{r^2 \sin^2 \theta} \right) + \left(\frac{2\nu}{r^2 \sin \theta} \right) \frac{\partial U_r}{\partial \phi} + \left(\frac{2\nu \cos \theta}{r^2 \sin^2 \theta} \right) \frac{\partial U_\theta}{\partial \phi} \end{aligned}$ (I)

¹ Brodkey, R.S. and Hershey H.C. (1988) *Transport Phenomena – A Unified Approach* Table 5.7 p147.

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Table 2: Shear stress-velocity gradient relationships for constant viscosity²

Rectangular coordinates

$$\tau_{xx} = -2\mu(\partial U_x/\partial x) + (2\mu/3)(\nabla \cdot U) \quad (\text{A})$$

$$\tau_{yy} = -2\mu(\partial U_y/\partial y) + (2\mu/3)(\nabla \cdot U) \quad (\text{B})$$

$$\tau_{zz} = -2\mu(\partial U_z/\partial z) + (2\mu/3)(\nabla \cdot U) \quad (\text{C})$$

$$\tau_{xy} = \tau_{yx} = -\mu[(\partial U_x/\partial y) + (\partial U_y/\partial x)] \quad (\text{D})$$

$$\tau_{yz} = \tau_{zy} = -\mu[(\partial U_y/\partial z) + (\partial U_z/\partial y)] \quad (\text{E})$$

$$\tau_{xz} = \tau_{zx} = -\mu[(\partial U_x/\partial z) + (\partial U_z/\partial x)] \quad (\text{F})$$

Cylindrical coordinates

$$\tau_{rr} = -2\mu(\partial U_r/\partial r) + (2\mu/3)(\nabla \cdot U) \quad (\text{G})$$

$$\tau_{\theta\theta} = -2\mu\left[\frac{1}{r}\left(\frac{\partial U_\theta}{\partial \theta}\right) + \frac{U_r}{r}\right] + (2\mu/3)(\nabla \cdot U) \quad (\text{H})$$

$$\tau_{zz} = -2\mu(\partial U_z/\partial z) + (2\mu/3)(\nabla \cdot U) \quad (\text{I})$$

$$\tau_{r\theta} = \tau_{\theta r} = -\mu\left[r\frac{\partial}{\partial r}\left(\frac{U_\theta}{r}\right) + \frac{1}{r}\left(\frac{\partial U_r}{\partial \theta}\right)\right] \quad (\text{J})$$

$$\tau_{\theta z} = \tau_{z\theta} = -\mu\left[\left(\frac{\partial U_\theta}{\partial z}\right) + \frac{1}{r}\left(\frac{\partial U_r}{\partial \theta}\right)\right] \quad (\text{K})$$

$$\tau_{rz} = \tau_{zr} = -\mu[(\partial U_r/\partial z) + (\partial U_z/\partial r)] \quad (\text{L})$$

Spherical coordinates

$$\tau_{rr} = -2\mu(\partial U_r/\partial r) + (2\mu/3)(\nabla \cdot U) \quad (\text{M})$$

$$\tau_{\theta\theta} = -2\mu\left[\frac{1}{r}\left(\frac{\partial U_\theta}{\partial \theta}\right) + \frac{U_r}{r}\right] + (2\mu/3)(\nabla \cdot U) \quad (\text{N})$$

$$\tau_{\phi\phi} = -2\mu\left[\frac{1}{r \sin \theta} \frac{\partial U_\phi}{\partial \phi} + \frac{U_r}{r} + (U_\theta/r)(\cot \theta)\right] + (2\mu/3)(\nabla \cdot U) \quad (\text{O})$$

$$\tau_{r\theta} = \tau_{\theta r} = -\mu\left[r\frac{\partial}{\partial r}\left(\frac{U_\theta}{r}\right) + \frac{1}{r}\left(\frac{\partial U_r}{\partial \theta}\right)\right] \quad (\text{P})$$

$$\tau_{\theta\phi} = \tau_{\phi\theta} = -\mu\left[\frac{\sin \theta}{r} \left[\frac{\partial}{\partial \theta} \left(\frac{U_\phi}{\sin \theta}\right)\right] + \frac{1}{r \sin \theta} \frac{\partial U_\theta}{\partial \phi}\right] \quad (\text{Q})$$

$$\tau_{r\phi} = \tau_{\phi r} = -\mu\left[\frac{1}{r \sin \theta} \frac{\partial U_r}{\partial \phi} + r \frac{\partial}{\partial r} \left(\frac{U_\phi}{r}\right)\right] \quad (\text{R})$$

² B&H *ibid* Table 5.2 p137.

Table 3: The energy equation³

General equation

$$\frac{\partial(\rho c_p T)}{\partial t} + (\mathbf{U} \cdot \nabla)(\rho c_p T) = \dot{I}_G + [\nabla \cdot \alpha \nabla(\rho c_p T)] - (\rho c_p T)(\nabla \cdot \mathbf{U}) \quad (5.13)$$

Incompressible media, rectangular coordinates

$$\frac{\partial T}{\partial t} + U_x \frac{\partial T}{\partial x} + U_y \frac{\partial T}{\partial y} + U_z \frac{\partial T}{\partial z} = \frac{\dot{I}_G}{\rho c_p} + \frac{\partial}{\partial x} \left(\alpha \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(\alpha \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(\alpha \frac{\partial T}{\partial z} \right) \quad (A)$$

Incompressible media, cylindrical coordinates

$$\frac{\partial T}{\partial t} + U_r \frac{\partial T}{\partial r} + \frac{U_\theta}{r} \frac{\partial T}{\partial \theta} + U_z \frac{\partial T}{\partial z} = \frac{\dot{I}_G}{\rho c_p} + \frac{1}{r} \frac{\partial}{\partial r} \left(r \alpha \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\alpha \frac{\partial T}{\partial \theta} \right) + \frac{\partial}{\partial z} \left(\alpha \frac{\partial T}{\partial z} \right) \quad (B)$$

Incompressible media, spherical coordinates

$$\begin{aligned} \frac{\partial T}{\partial t} + U_r \frac{\partial T}{\partial r} + \frac{U_\theta}{r} \frac{\partial T}{\partial \theta} + \frac{U_\phi}{r \sin \theta} \frac{\partial T}{\partial \phi} &= \frac{\dot{I}_G}{\rho c_p} + \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \alpha \frac{\partial T}{\partial r} \right) \\ &+ \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\alpha \sin \theta \frac{\partial T}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \phi} \left(\alpha \frac{\partial T}{\partial \phi} \right) \end{aligned} \quad (C)$$

Table 4: The continuity equation for species A⁴

General equation

$$\frac{\partial C_A}{\partial t} + (\mathbf{U} \cdot \nabla) C_A = \dot{C}_{A,G} + (\nabla \cdot D \nabla C_A) - (C_A)(\nabla \cdot \mathbf{U}) \quad (5.8)$$

Incompressible media, rectangular coordinates

$$\frac{\partial C_A}{\partial t} + U_x \frac{\partial C_A}{\partial x} + U_y \frac{\partial C_A}{\partial y} + U_z \frac{\partial C_A}{\partial z} = \dot{C}_{A,G} + \frac{\partial}{\partial x} \left(D \frac{\partial C_A}{\partial x} \right) + \frac{\partial}{\partial y} \left(D \frac{\partial C_A}{\partial y} \right) + \frac{\partial}{\partial z} \left(D \frac{\partial C_A}{\partial z} \right) \quad (A)$$

Incompressible media, cylindrical coordinates

$$\frac{\partial C_A}{\partial t} + U_r \frac{\partial C_A}{\partial r} + \frac{U_\theta}{r} \frac{\partial C_A}{\partial \theta} + U_z \frac{\partial C_A}{\partial z} = \dot{C}_{A,G} + \frac{1}{r} \frac{\partial}{\partial r} \left(r D \frac{\partial C_A}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(D \frac{\partial C_A}{\partial \theta} \right) + \frac{\partial}{\partial z} \left(D \frac{\partial C_A}{\partial z} \right) \quad (B)$$

Incompressible media, spherical coordinates

$$\begin{aligned} \frac{\partial C_A}{\partial t} + U_r \frac{\partial C_A}{\partial r} + \frac{U_\theta}{r} \frac{\partial C_A}{\partial \theta} + \frac{U_\phi}{r \sin \theta} \frac{\partial C_A}{\partial \phi} &= \dot{C}_{A,G} + \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 D \frac{\partial C_A}{\partial r} \right) \\ &+ \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(D \sin \theta \frac{\partial C_A}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \phi} \left(D \frac{\partial C_A}{\partial \phi} \right) \end{aligned} \quad (C)$$

³ B&H *ibid* Table 5.6 p143.

⁴ B&H *ibid* Table 5.4 p142.