

National Exams December 2014
04-CHEM-B1, Transport Phenomena
3 hours duration

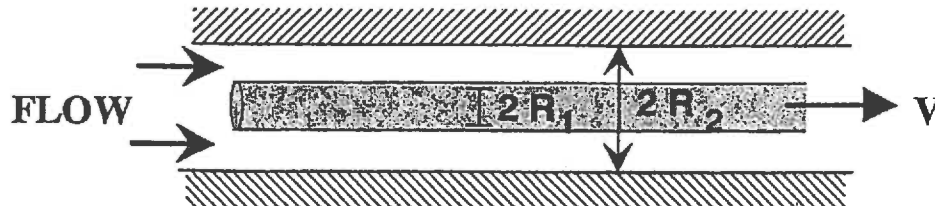
NOTES

1. If doubt exists as to the interpretation of any question, the candidate is urged to submit with the answer paper, a clear statement of any assumptions made.
2. The examination is an OPEN BOOK EXAM.
3. Candidates may use any **non-communicating** calculator.
4. All problems are worth 25 points. **One problem** from **each** of sections A, B, and C must be attempted. A **fourth** problem from **any section** must also be attempted.
5. **Only the first four** questions as they appear in the answer book will be marked.
6. State all assumptions clearly.

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Section A: Fluid Mechanics

- A1.** The barrel of an extruder can be modeled as if a solid rod is moving with a velocity V through a fluid inside a horizontal cylindrical tube as shown in the figure below.



There is also a pressure gradient imposed on the fluid in the annulus (gap between the solid rod and the cylindrical tube).

- a) [15 points] Derive an expression for the steady-state velocity distribution for fully developed laminar flow of a Newtonian fluid in the annulus for tube/rod length L .
- b) [10 points] What is the steady-state velocity distribution for fully developed laminar flow of a Newtonian fluid in the annulus for tube/rod length L if the rod is also stationary?
- A2.** Dimples on a golf ball cause a drop in the drag force at lower Reynolds number. The table below gives the drag coefficient (C_D) for a rough sphere as a function of Reynolds number (Re).

| | | | | | |
|---------------------|------|------|------|------|------|
| $Re \times 10^{-4}$ | 7.5 | 10 | 15 | 20 | 25 |
| C_D | 0.48 | 0.38 | 0.22 | 0.12 | 0.10 |

Using a kinematic viscosity (ν) value of $1.69 \times 10^{-4} \text{ ft}^2/\text{s}$ for air,

- a) [12 points] Calculate the drag force as a function of velocity for a “dimpled” golf ball of 1.65-inch diameter.
- b) [13 points] Calculate the drag force for a 1.65-inch “smooth” sphere as a function of velocity, and compare your results with (a).

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Section B: Heat Transfer

- B1.** The temperatures at the inner and outer surfaces of a plane wall of thickness L are held at the constant values of T_0 and T_L , where $T_0 > T_L$. The wall material has a thermal conductivity (k) that varies linearly given by the following equation:

$$k = k_0 (1 + \beta T)$$

where k_0 and β are constants.

- a) [15 points] At what position will the actual temperature profile differ the most from that which would exist in the case of constant thermal conductivity?
- b) [10 points] Repeat (a) for the case of a hollow cylinder with boundary conditions $T = T_0$ at $r = R_0$ and $T = T_L$ at $r = R_0 + L$.
- B2.** An apparatus used in a medical operating room to cool blood consists of a coiled tube, which is immersed, in an ice bath. Using this apparatus, blood, flowing at 6 liters/hr, is to be cooled from 40 °C to 30 °C. The inside diameter of the tube is 2.5 mm and the surface coefficient between the ice bath and outside tube surface is 500 W/m². The thermal resistance of the tube wall may be neglected. Determine the required length of tubing to accomplish the desired cooling using the following properties for blood:

$$\text{Density } (\rho) = 1000 \text{ g/cc}$$

$$\text{Thermal Conductivity } (k) = 0.5 \text{ W/m.K}$$

$$\text{Specific Heat Capacity } (c_p) = 4.0 \text{ kJ/kg.K}$$

$$\text{Kinematic Viscosity } (\nu) = 7 \times 10^{-7} \text{ m}^2/\text{s}$$

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Section C: Mass Transfer

C1. One way to deliver a timed dosage of a drug within the human body is to ingest a capsule and allow it to settle in the gastrointestinal system. Once inside the body, the capsule slowly releases the drug to the body by a diffusion-limited process. A suitable drug carrier is a spherical bead of a non-toxic gelatinous material that can pass through the gastrointestinal system without disintegrating. A water-soluble drug (solute A) is uniformly dissolved within the gel, and has an initial concentration (C_{A0}) of 50 mg/cm^3 . The drug loaded within the spherical gel capsule is the source of mass transfer, whereas the fluid surrounding the capsule is the sink for mass transfer. Consider a limiting case where the drug is immediately consumed or swept away once it reaches the surface.

- a) **[10 points]** Sketch a picture of the physical system and state at least five reasonable assumptions on the mass-transfer aspects of the drug-release process.
- b) **[5 points]** What is the simplified differential form of Fick's equation for the drug (species A) within the spherical gel capsule at the surface of the capsule?
- c) **[10 points]** What is the simplified form of the general differential equation for mass transfer in terms of concentration C_A ? Propose reasonable boundary and initial conditions that may be used to solve the resulting differential equation.

C2. A drop of liquid toluene (A) is kept at a uniform temperature of $25.9 \text{ }^\circ\text{C}$, and it is suspended in air (B) by a fine wire at 1 atmosphere total pressure. The initial radius of the drop (r_1) is 2 mm. The vapor pressure of toluene (P_{A1}) at $25.9 \text{ }^\circ\text{C}$ is 3.84 kPa and the density of liquid toluene (ρ_A) is 866 kg/m^3 .

- a) **[15 points]** Derive the following equation to predict the time t_f for the drop to evaporate completely in a large volume of still air:

$$t_f = (\rho_A r_1^2 R T P_{BM}) / [2 M_A D_{AB} P (P_{A1} - P_{A2})]$$

where M_A is the molecular weight of the liquid droplet and P_{BM} is the log mean pressure difference of air.

- b) **[10 points]** For $D_{AB} = 8.6 \times 10^{-6} \text{ m}^2/\text{s}$, calculate the time (in seconds) for complete evaporation of the liquid toluene drop. The molecular weight of toluene is 92.14 g/mol.

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APPENDIX A

Summary of the Conservation Equations

Table A.1 The Continuity Equation

| |
|---|
| $\frac{\partial \rho}{\partial t} + (\nabla \cdot \rho \vec{u}) = 0 \quad (1.1)$ |
| <p>Rectangular coordinates (x, y, z)</p> $\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x}(\rho u_x) + \frac{\partial}{\partial y}(\rho u_y) + \frac{\partial}{\partial z}(\rho u_z) = 0 \quad (1.1a)$ |
| <p>Cylindrical coordinates (r, θ, z)</p> $\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r}(\rho r u_r) + \frac{1}{r} \frac{\partial}{\partial \theta}(\rho u_\theta) + \frac{\partial}{\partial z}(\rho u_z) = 0 \quad (1.1b)$ |
| <p>Spherical coordinates (r, θ, ϕ)</p> $\frac{\partial \rho}{\partial t} + \frac{1}{r^2} \frac{\partial}{\partial r}(\rho r^2 u_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta}(\rho u_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi}(\rho u_\phi) = 0 \quad (1.1c)$ |

Table A.2 The Navier-Stokes equations for Newtonian fluids of constant ρ and μ

| |
|---|
| $\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} = -\frac{1}{\rho} \nabla P + \vec{g} + \nu (\nabla^2 \vec{u}) \quad (A2)$ |
| <p>Rectangular coordinates (x, y, z)</p> |
| <p>x-component</p> $\frac{\partial u_x}{\partial t} + u_x \frac{\partial u_x}{\partial x} + u_y \frac{\partial u_x}{\partial y} + u_z \frac{\partial u_x}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial x} + g_x + \nu \left(\frac{\partial^2 u_x}{\partial x^2} + \frac{\partial^2 u_x}{\partial y^2} + \frac{\partial^2 u_x}{\partial z^2} \right) \quad (A2a)$ |
| <p>y-component</p> $\frac{\partial u_y}{\partial t} + u_x \frac{\partial u_y}{\partial x} + u_y \frac{\partial u_y}{\partial y} + u_z \frac{\partial u_y}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial y} + g_y + \nu \left(\frac{\partial^2 u_y}{\partial x^2} + \frac{\partial^2 u_y}{\partial y^2} + \frac{\partial^2 u_y}{\partial z^2} \right) \quad (A2b)$ |
| <p>z-component</p> $\frac{\partial u_z}{\partial t} + u_x \frac{\partial u_z}{\partial x} + u_y \frac{\partial u_z}{\partial y} + u_z \frac{\partial u_z}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial z} + g_z + \nu \left(\frac{\partial^2 u_z}{\partial x^2} + \frac{\partial^2 u_z}{\partial y^2} + \frac{\partial^2 u_z}{\partial z^2} \right) \quad (A2c)$ |

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Cylindrical coordinates (r, θ, z)

$$\begin{aligned} r\text{-component} \quad & \frac{\partial u_r}{\partial t} + u_r \frac{\partial u_r}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_r}{\partial \theta} + u_z \frac{\partial u_r}{\partial z} - \frac{u_\theta^2}{r} \\ & = -\frac{1}{\rho} \frac{\partial P}{\partial r} + g_r + \nu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (ru_r)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial u_\theta}{\partial \theta} + \frac{\partial^2 u_r}{\partial z^2} \right] \end{aligned} \quad (\text{A2d})$$

$$\begin{aligned} \theta\text{-component} \quad & \frac{\partial u_\theta}{\partial t} + u_r \frac{\partial u_\theta}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_\theta}{\partial \theta} + u_z \frac{\partial u_\theta}{\partial z} + \frac{u_r u_\theta}{r} \\ & = -\frac{1}{\rho r} \frac{\partial P}{\partial \theta} + g_\theta + \nu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (ru_\theta)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} + \frac{\partial^2 u_\theta}{\partial z^2} \right] \end{aligned} \quad (\text{A2e})$$

$$\begin{aligned} z\text{-component} \quad & \frac{\partial u_z}{\partial t} + u_r \frac{\partial u_z}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_z}{\partial \theta} + u_z \frac{\partial u_z}{\partial z} \\ & = -\frac{1}{\rho} \frac{\partial P}{\partial z} + g_z + \nu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u_z}{\partial \theta^2} + \frac{\partial^2 u_z}{\partial z^2} \right] \end{aligned} \quad (\text{A2f})$$

Spherical coordinates (r, θ, ϕ)

$$\begin{aligned} r\text{-component} \quad & \frac{\partial u_r}{\partial t} + u_r \frac{\partial u_r}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_r}{\partial \theta} + \left(\frac{u_\phi}{r \sin \theta} \right) \frac{\partial u_r}{\partial \phi} - \frac{u_\theta^2}{r} - \frac{u_\phi^2}{r} = -\frac{1}{\rho} \frac{\partial P}{\partial r} + g_r \\ & + \nu \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 u_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial u_r}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_r}{\partial \phi^2} \right] \end{aligned} \quad (\text{A2g})$$

$$\begin{aligned} \theta\text{-component} \quad & \frac{\partial u_\theta}{\partial t} + u_r \frac{\partial u_\theta}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_\theta}{\partial \theta} + \left(\frac{u_\phi}{r \sin \theta} \right) \frac{\partial u_\theta}{\partial \phi} + \frac{u_r u_\theta}{r} - \frac{u_\phi^2}{r} \cot \theta = -\frac{1}{\rho r} \frac{\partial P}{\partial \theta} + g_\theta \\ & + \nu \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial u_\theta}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (u_\theta \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_\theta}{\partial \phi^2} \right. \\ & \left. + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right] \end{aligned} \quad (\text{A2h})$$

$$\begin{aligned} \phi\text{-component} \quad & \frac{\partial u_\phi}{\partial t} + u_r \frac{\partial u_\phi}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} + \frac{u_r u_\phi}{r} + \frac{u_\theta u_\phi}{r} \cot \theta = -\frac{1}{\rho r \sin \theta} \frac{\partial P}{\partial \phi} \\ & + g_\phi + \nu \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial u_\phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (u_\phi \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_\phi}{\partial \phi^2} \right. \\ & \left. + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial u_\theta}{\partial \phi} \right] \end{aligned} \quad (\text{A2i})$$

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Table A.3 The Energy Equation for Incompressible Media

| |
|---|
| $\rho c_p \left[\frac{\partial T}{\partial t} + (\vec{u} \cdot \nabla)(T) \right] = [\nabla \cdot k \nabla T] + \dot{T}_G \quad (\text{A3})$ |
| <p>Rectangular coordinates (x, y, z)</p> $\rho c_p \left[\frac{\partial T}{\partial t} + u_x \frac{\partial T}{\partial x} + u_y \frac{\partial T}{\partial y} + u_z \frac{\partial T}{\partial z} \right] = \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \dot{T}_G \quad (\text{A3a})$ |
| <p>Cylindrical coordinates (r, θ, z)</p> $\rho c_p \left[\frac{\partial T}{\partial t} + u_r \frac{\partial T}{\partial r} + \frac{u_\theta}{r} \frac{\partial T}{\partial \theta} + u_z \frac{\partial T}{\partial z} \right] = \frac{1}{r} \frac{\partial}{\partial r} \left(r k \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(k \frac{\partial T}{\partial \theta} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \dot{T}_G \quad (\text{A3b})$ |
| <p>Spherical coordinates (r, θ, φ)</p> $\rho c_p \left[\frac{\partial T}{\partial t} + u_r \frac{\partial T}{\partial r} + \frac{u_\theta}{r} \frac{\partial T}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial T}{\partial \phi} \right] =$ $\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 k \frac{\partial T}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(k \sin \theta \frac{\partial T}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \phi} \left(k \frac{\partial T}{\partial \phi} \right) + \dot{T}_G \quad (\text{A3c})$ |

Table A4: The continuity equation for species A in terms of the molar flux

| |
|---|
| $\frac{\partial C_A}{\partial t} = -(\nabla \cdot \vec{N}_A) + \dot{R}_{A,G} \quad (4.)$ |
| <p>Rectangular coordinates (x, y, z)</p> $\frac{\partial C_A}{\partial t} = - \left(\frac{\partial [N_A]_x}{\partial x} + \frac{\partial [N_A]_y}{\partial y} + \frac{\partial [N_A]_z}{\partial z} \right) + \dot{R}_{A,G} \quad (4a)$ |
| <p>Cylindrical coordinates (r, θ, z)</p> $\frac{\partial C_A}{\partial t} = - \left\{ \frac{1}{r} \frac{\partial}{\partial r} [r N_A]_r + \frac{1}{r} \frac{\partial}{\partial \theta} [N_A]_\theta + \frac{\partial}{\partial z} [N_A]_z \right\} + \dot{R}_{A,G} \quad (4b)$ |
| <p>Spherical coordinates (r, θ, φ)</p> $\frac{\partial C_A}{\partial t} = - \left\{ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 [N_A]_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} ([N_A]_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} [N_A]_\phi \right\} + \dot{R}_{A,G} \quad (4c)$ |

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Table A.5: The continuity equation for species A

| |
|---|
| $\frac{\partial C_A}{\partial t} + (\bar{u} \cdot \nabla) C_A = D_A \nabla^2 C_A + \dot{R}_{A,G} \quad (5)$ |
| <p>Rectangular coordinates (x, y, z)</p> $\frac{\partial C_A}{\partial t} + u_x \frac{\partial C_A}{\partial x} + u_y \frac{\partial C_A}{\partial y} + u_z \frac{\partial C_A}{\partial z} = \frac{\partial}{\partial x} \left(D \frac{\partial C_A}{\partial x} \right) + \frac{\partial}{\partial y} \left(D \frac{\partial C_A}{\partial y} \right) + \frac{\partial}{\partial z} \left(D \frac{\partial C_A}{\partial z} \right) + \dot{R}_{A,G} \quad (5a)$ |
| <p>Cylindrical coordinates (r, θ, z)</p> $\frac{\partial C_A}{\partial t} + u_r \frac{\partial C_A}{\partial r} + \frac{u_\theta}{r} \frac{\partial C_A}{\partial \theta} + u_z \frac{\partial C_A}{\partial z} = \frac{1}{r} \frac{\partial}{\partial r} \left(r D \frac{\partial C_A}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(D \frac{\partial C_A}{\partial \theta} \right) + \frac{\partial}{\partial z} \left(D \frac{\partial C_A}{\partial z} \right) + \dot{R}_{A,G} \quad (5b)$ |
| <p>Spherical coordinates (r, θ, ϕ)</p> $\frac{\partial C_A}{\partial t} + u_r \frac{\partial C_A}{\partial r} + \frac{u_\theta}{r} \frac{\partial C_A}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial C_A}{\partial \phi} = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 D \frac{\partial C_A}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(D \sin \theta \frac{\partial C_A}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \phi} \left(D \frac{\partial C_A}{\partial \phi} \right) + \dot{R}_{A,G} \quad (5c)$ |